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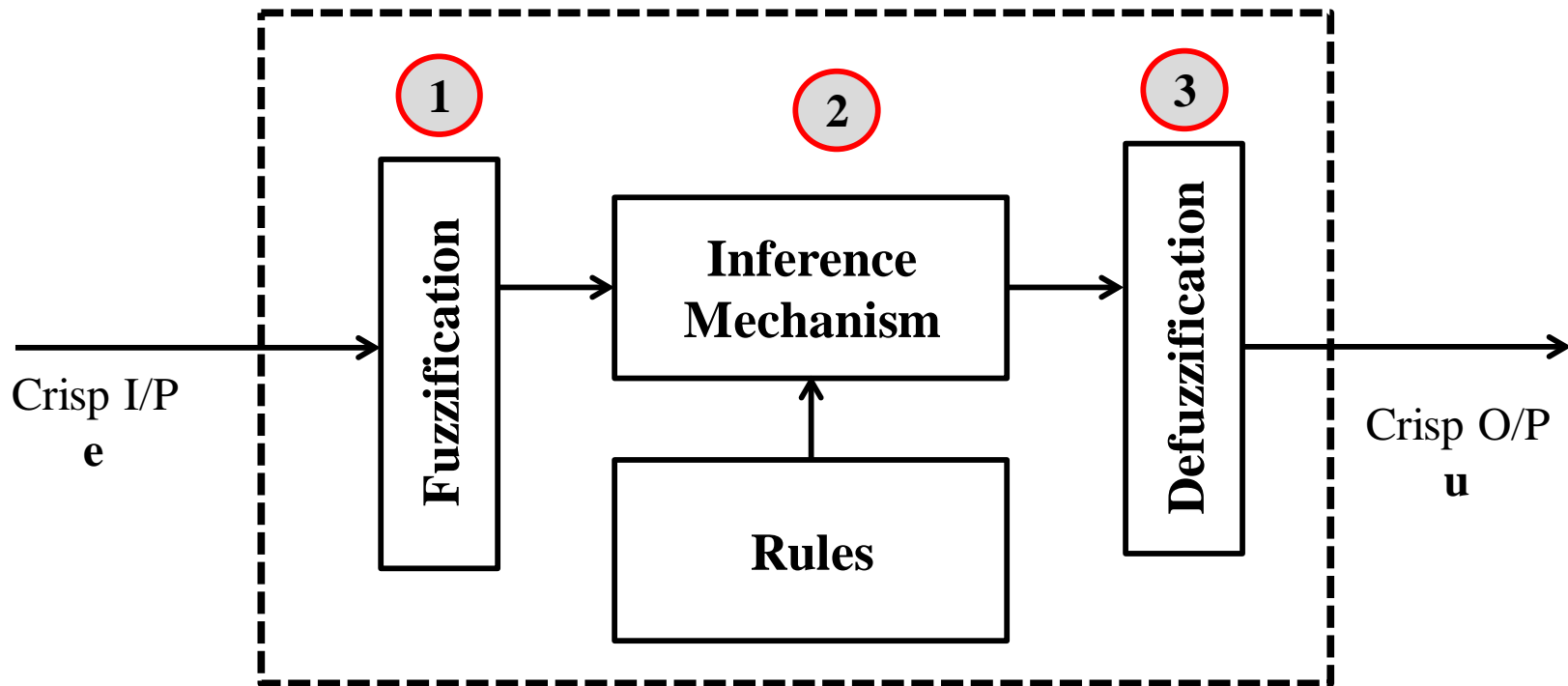
# **Fuzzy Control Course**

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## **Lec 6**

8/11/2016

# Fuzzy Controller Structure



## Fuzzy Controller

- Crisp means numeric (or real) value

## Fuzzy Inference System (Controller)

- Inference is the process of formulating a nonlinear mapping from a given crisp input to a crisp output. The mapping then provides a basis from which decisions can be made. The process of fuzzy inference involves all the membership functions (fuzzy sets), operators and IF–THEN rules.
- **There are three types of fuzzy inference** which have been widely employed in various fuzzy systems and applications. These fuzzy inferences (models/controllers) are: **(1) Mamdani fuzzy inference**  
**(2) Sugeno fuzzy inference**  
**(3) Tsukamoto fuzzy inference**

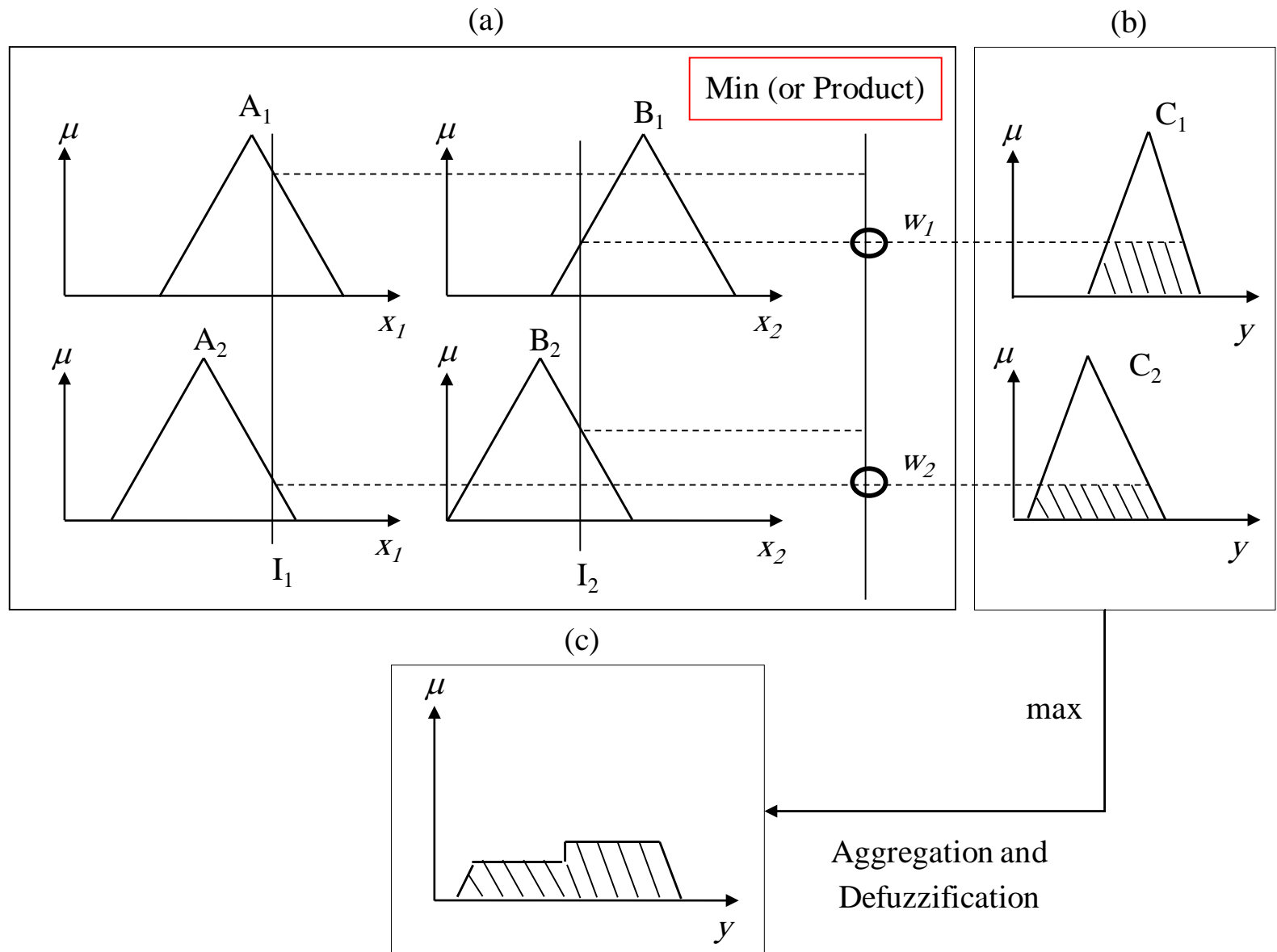
The most commonly-used are Mamdani-type and Sugeno-type.

## (1) Mamdani Fuzzy Inference

- The Mamdani-type fuzzy inference was first proposed as an attempt to control a steam engine and boiler using a set of linguistic control rules obtained from an experienced human operator.
- **EX:** To illustrate the Mamdani-type fuzzy mechanism, consider a two input single-output Mamdani fuzzy model, each input  $x_1$ ,  $x_2$  and output  $y$  has two MFs: {A1, A2}, {B1, B2} and {C1, C2}, respectively. If we consider two rules  $R_1$  and  $R_2$ , these rules are:

$R_1$  : IF  $x_1$  is A1 AND  $x_2$  is B1 THEN  $y$  is  $C_1$

$R_2$  : IF  $x_1$  is A2 AND  $x_2$  is B2 THEN  $y$  is  $C_2$



**Fig. 1 Two-input single-output Mamdani fuzzy model**

## (1) Mamdani Fuzzy Inference

- In the Mamdani -type fuzzy model shown in Fig.1, two measured crisp values  $I_1$  and  $I_2$  are used for the inputs  $x_1$  and  $x_2$ , respectively.
- Fig.1-a shows the fuzzification and inferencing using the minimum rule (AND operator in the IF-Part can be represented using Min. or product rule) for computing the firing strengths  $w_1$  and  $w_2$  for the premise terms of the rules.

$$\begin{array}{l} \text{or} \\ w_1 = \min(\mu_{A1}, \mu_{B1}) \quad , \quad w_2 = \min(\mu_{A2}, \mu_{B2}) \\ w_1 = \mu_{A1} \cdot \mu_{B1} \quad , \quad w_2 = \mu_{A2} \cdot \mu_{B2} \end{array}$$

- $w_1$  and  $w_2$  are stand for  $\mu_{\text{Premise1}}$  and  $\mu_{\text{Premise2}}$  as we used before, these weights represent the strengths for the firing rules.

## (1) Mamdani Fuzzy Inference

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- The inferred output of each rule is the truncated membership functions chosen from the minimum firing strength as shown in Fig.1-b. The truncated membership functions for each rule are aggregated as shown in Fig.1-c and any of the following defuzzification methods (like Center of gravity (COG)) is carried out to convert a fuzzy set to a crisp value, these methods are:
  - Center of Gravity (COG) method
  - Weighted average method
  - Mean-max membership method

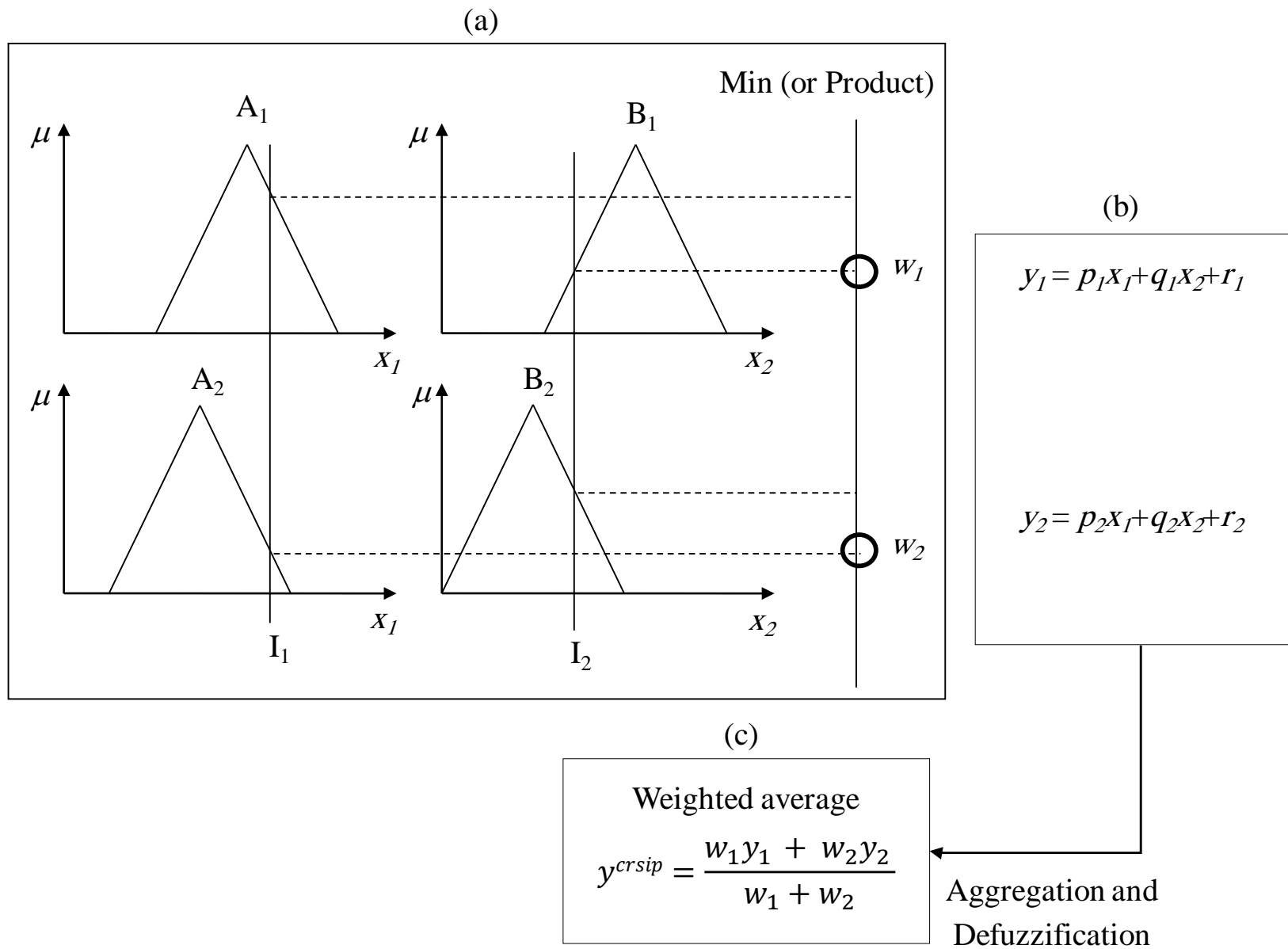


## (2) Sugeno Fuzzy Inference / TSK Fuzzy Inference

- The Sugeno fuzzy inference, also known as the TSK fuzzy model, was proposed by Takagi, Sugeno and Kang in 1985.
- The output of each rule of the fuzzy IF-THEN rules (consequent or then part) is a linear function which is a combination of input variables plus a constant term.
- **EX:** To illustrate the Sugeno-type inferencing mechanism, consider a two- input single-output TSK fuzzy model, each input  $x_1$  and  $x_2$  has two membership functions (MFs)  $\{A1, A2\}$  and  $\{B1, B2\}$ , if we consider two rules  $R_1$  and  $R_2$  with consequent functions  $\{y_1, y_2\}$ . These rules are:

$$R_1 : \text{IF } x_1 \text{ is } A1 \text{ AND } x_2 \text{ is } B1 \text{ THEN } y_1 = p_1 x_1 + q_1 x_2 + r_1$$

$$R_2 : \text{IF } x_1 \text{ is } A2 \text{ AND } x_2 \text{ is } B2 \text{ THEN } y_2 = p_2 x_1 + q_2 x_2 + r_2$$



**Fig. 2 Two-input single-output TSK fuzzy model**

## (2) Sugeno Fuzzy Inference / TSK Fuzzy Inference

- In the Sugeno-type fuzzy model shown in Fig.2, two measured crisp values  $I_1$  and  $I_2$  are used for the inputs  $x_1$  and  $x_2$ , respectively.
- Fig. 2-a shows the fuzzification and inferencing using the minimum or product rule for computing the firing strengths  $w_1$  and  $w_2$  for the premise term of the rules. The firing strength is calculated using the minimum or product rule as:

$$\begin{array}{ll} w_1 = \min(\mu_{A1}, \mu_{B1}) & , \quad w_2 = \min(\mu_{A2}, \mu_{B2}) \\ \text{or} & \\ w_1 = \mu_{A1} \cdot \mu_{B1} & , \quad w_2 = \mu_{A2} \cdot \mu_{B2} \end{array}$$

- $w_1$  and  $w_2$  are stand for  $\mu_{\text{Premise1}}$  and  $\mu_{\text{Premise2}}$  as we used before, these weights represent the strengths for the firing rules.

## (2) Sugeno Fuzzy Inference / TSK Fuzzy Inference

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- Once the parameters  $\{p_1, q_1, r_1, p_2, q_2, r_2\}$  are known, the consequent  $y_1$  and  $y_2$  are calculated for each rule using a first-order polynomial as shown in fig.2-b. The overall output  $y$  is obtained via the weighted average of the crisp outputs  $y_1$  and  $y_2$ . The weighted average defuzzification method is computed by:

$$y^{\text{crisp}} = \frac{w_1 y_1 + w_2 y_2}{w_1 + w_2}$$

- Fig.2-c illustrates the aggregation and final defuzzified value for the TSK model.

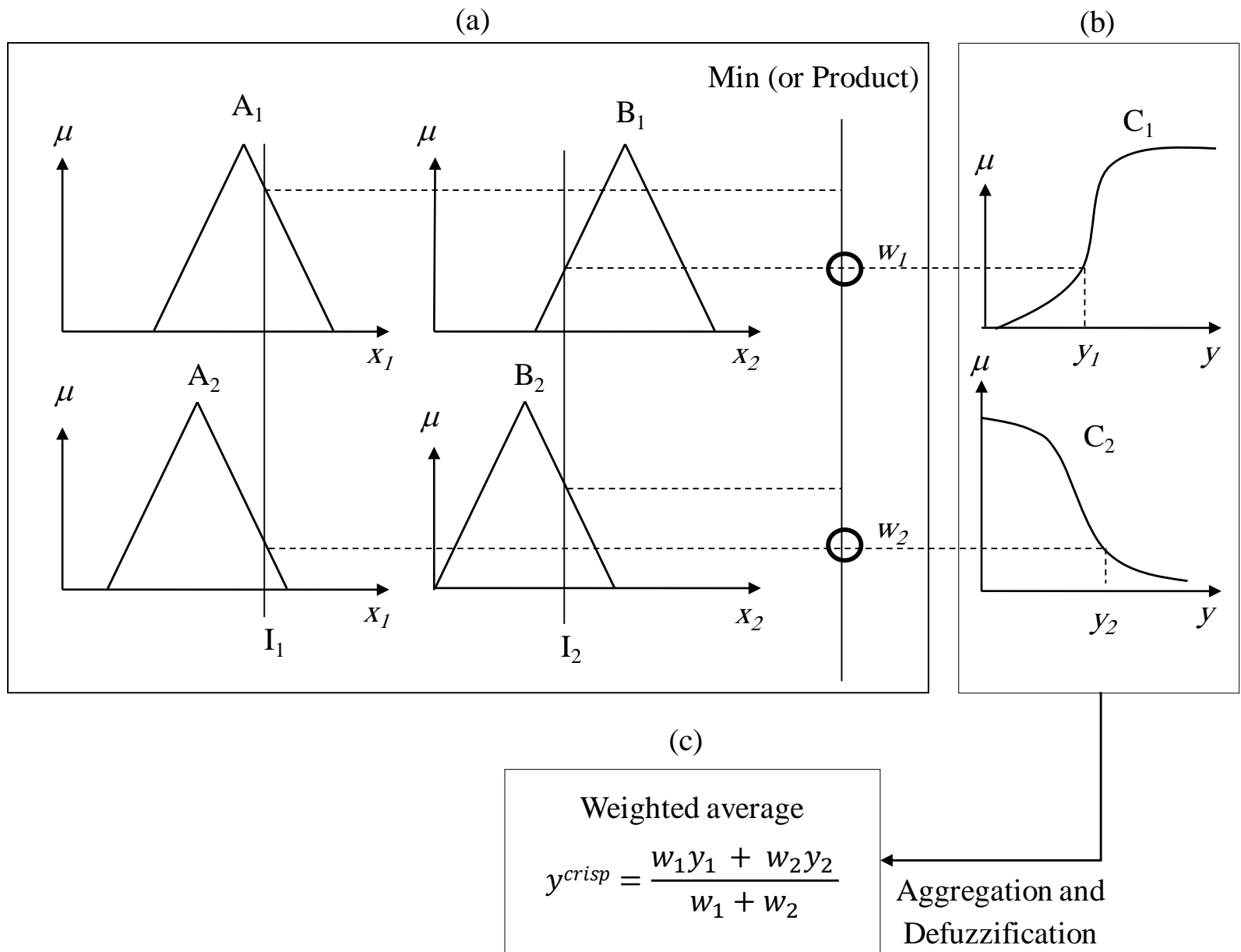
### (3) Tsukamoto Fuzzy Inference

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- In the Tsukamoto fuzzy inference, the consequent of each fuzzy if–then rule is represented by a monotonic MF (function between ordered sets that preserves the given order).
- **EX:** To illustrate the Tsukamoto-type mechanism, consider a two input single-output Tsukamoto fuzzy model, each input  $x_1$  and  $x_2$  has two membership functions (MFs)  $\{A1, A2\}$  and  $\{B1, B2\}$ , if we consider two rules  $R_1$  and  $R_2$  with consequent monotonic functions  $\{C_1, C_2\}$ . These rules are:

$R_1$ : IF  $x_1$  is  $A1$  AND  $x_2$  is  $B1$  THEN  $y$  is  $C_1$

$R_2$ : IF  $x_1$  is  $A2$  AND  $x_2$  is  $B2$  THEN  $y$  is  $C_2$



**Fig. 3 Two-input single-output Tsukamoto fuzzy model**

### (3) Tsukamoto Fuzzy Inference

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- In the Tsukamoto-type fuzzy model shown in Fig.3, two measured crisp values  $I_1$  and  $I_2$  are used for the inputs  $x_1$  and  $x_2$ , respectively.
- Fig.3-a shows the fuzzification and inferencing using the minimum or product rule for computing the firing strengths  $w_1$  and  $w_2$  for the premise term of the rules. The firing strength is calculated using the minimum or product rule.
- The consequent  $y_1$  and  $y_2$  represent the defuzzified outputs (one value for each rule) and are determined as shown in fig.3-b.
- The overall output  $y$  is obtained via the weighted average of the crisp outputs  $y_1$  and  $y_2$ .

### (3) Tsukamoto Fuzzy Inference

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- The overall output  $y$  is obtained via the weighted average of the crisp outputs  $y_1$  and  $y_2$ . The weighted average defuzzification method is computed by:

$$y^{\text{crisp}} = \frac{w_1 y_1 + w_2 y_2}{w_1 + w_2}$$

- Fig.3-c illustrates the defuzzified value for the Tsukamoto model.
- **Despite the simplification of the defuzzification procedure, the Tsukamoto fuzzy model is not used very often.**



## Example: Steam Engine System Using TSK-fuzzy Model

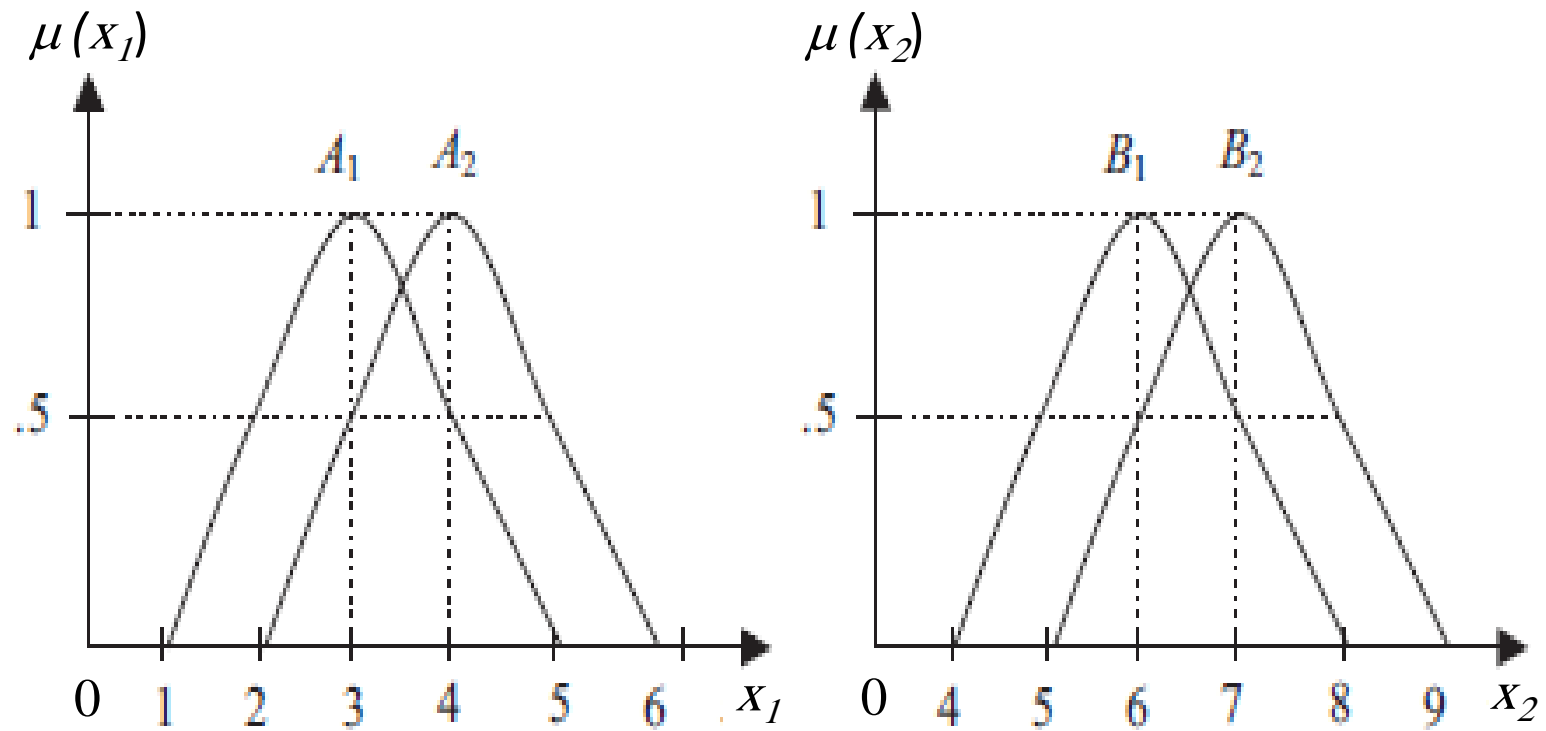
- A steam engine system has been developed using a Takagi–Sugeno fuzzy model, where  $x_1$  represents speed,  $x_2$  represents pressure and  $y$  represents throttle position.
- Two membership functions for speed  $x_1$  and pressure  $x_2$ , defined within the same universe of discourse  $[0, 10]$ , are shown in Fig. 4. For the linguistic variable  $x_1$ , the MFs are taken to be  $\{A1, A2\}$  and for  $x_2$ , the MFs are taken to be  $\{B1, B2\}$ . The throttle position  $y$  is defined by the four first-order polynomial functions below:

$$y_1 = 3x_1 + 2x_2 + 1$$

$$y_2 = x_1 + 3x_2 + 1$$

$$y_3 = x_1 + 2x_2$$

$$y_4 = 2x_1 + 5$$



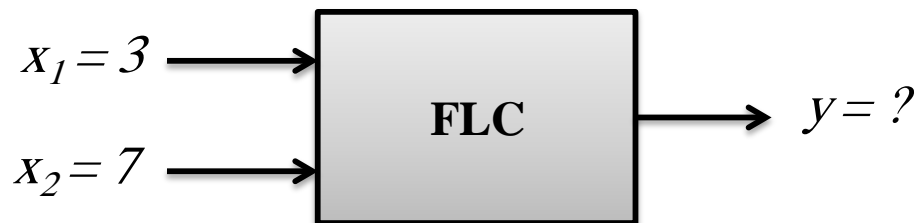
**Fig. 4: MFs for inputs  $x_1$  and  $x_2$**

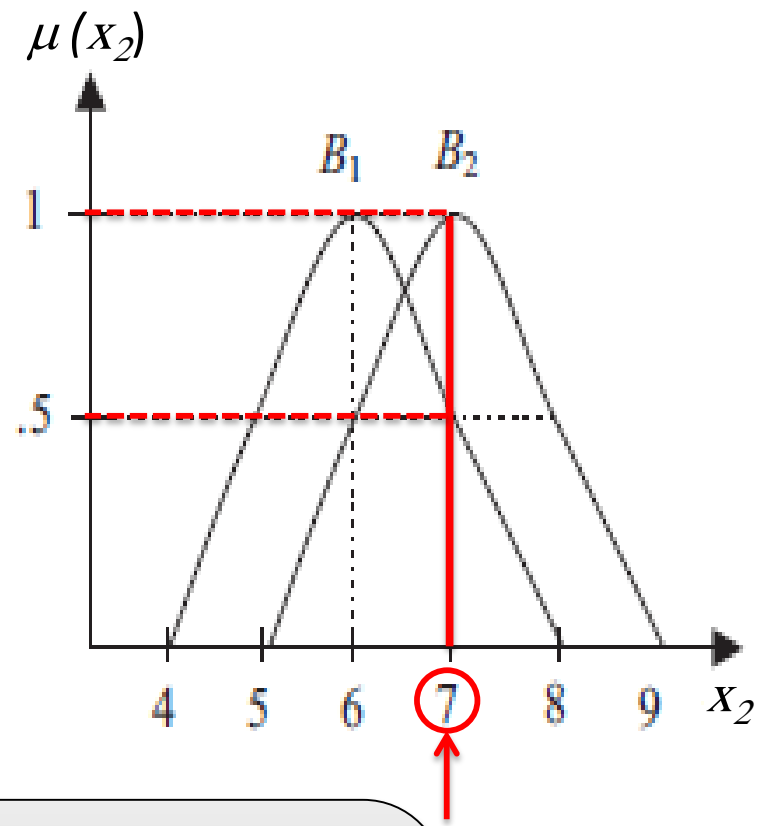
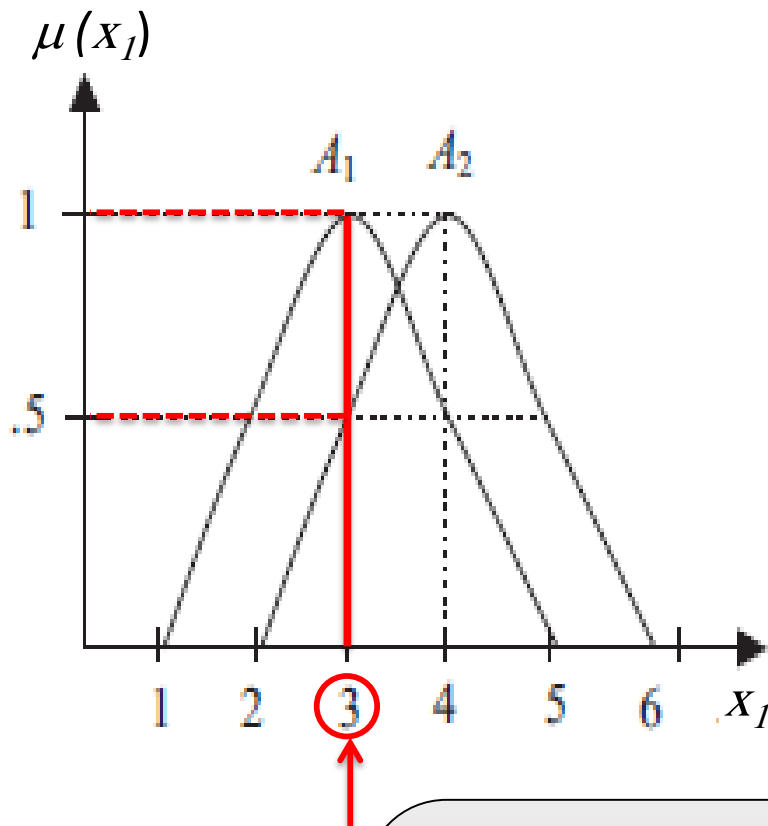
## Example: Steam Engine System Using TSK-fuzzy Model

- The rule base of the TSK-fuzzy model consists of four rules, as shown in the following table:

| $x_1 \backslash x_2$ | $B1$  | $B2$  |
|----------------------|-------|-------|
| $A1$                 | $y_1$ | $y_2$ |
| $A2$                 | $y_3$ | $y_4$ |

- Find the throttle position  $y$ , if the inputs take values  $x_1 = 3$  and  $x_2 = 7$ .





### 1- Fuzzification

$x_1$  is  $A1$  with  $\mu_{A_1}(x_1 = 3) = 1$

$x_1$  is  $A2$  with  $\mu_{A_2}(x_1 = 3) = 0.5$

$x_2$  is  $B1$  with  $\mu_{B_1}(x_2 = 7) = 0.5$

$x_2$  is  $B2$  with  $\mu_{B_2}(x_2 = 7) = 1$

## 2- The Fired Rules:

R1: IF  $x_1$  is  $A1$  AND  $x_2$  is  $B1$  THEN  $y_1 = 3x_1 + 2x_2 + 1$

R2: IF  $x_1$  is  $A1$  AND  $x_2$  is  $B2$  THEN  $y_2 = x_1 + 3x_2 + 1$

R3: IF  $x_1$  is  $A2$  AND  $x_2$  is  $B1$  THEN  $y_3 = x_1 + 2x_2$

R4: IF  $x_1$  is  $A2$  AND  $x_2$  is  $B2$  THEN  $y_4 = 2x_1 + 5$

**Where at  $x_1 = 3$  ,  $x_2 = 7$  :**

$$y_1 = 3*3 + 2*7 + 1 = 24$$

$$y_2 = 3 + 3*7 + 1 = 25$$

$$y_3 = 3 + 2*7 = 17$$

$$y_4 = 2*3 + 5 = 11$$

## 2- The Fired Rules:

R1: IF  $x_1$  is  $A1$  AND  $x_2$  is  $B1$  THEN  $y_1 = 24$

R2: IF  $x_1$  is  $A1$  AND  $x_2$  is  $B2$  THEN  $y_2 = 25$

R3: IF  $x_1$  is  $A2$  AND  $x_2$  is  $B1$  THEN  $y_3 = 17$

R4: IF  $x_1$  is  $A2$  AND  $x_2$  is  $B2$  THEN  $y_4 = 11$

## 3- The strength of the fired rules:

R1:  $w_1 = \mu_{\text{premise1}} = \min \{ \mu_{A1}(x_1), \mu_{B1}(x_2) \} = \min \{ 1, 0.5 \} = 0.5$

R2:  $w_2 = \mu_{\text{premise2}} = \min \{ \mu_{A1}(x_1), \mu_{B2}(x_2) \} = \min \{ 1, 1 \} = 1$

R3:  $w_3 = \mu_{\text{premise3}} = \min \{ \mu_{A2}(x_1), \mu_{B1}(x_2) \} = \min \{ 0.5, 0.5 \} = 0.5$

R4:  $w_4 = \mu_{\text{premise4}} = \min \{ \mu_{A2}(x_1), \mu_{B2}(x_2) \} = \min \{ 0.5, 1 \} = 0.5$

#### 4- Aggregation and Defuzzification:

R1:  $y_1 = 24$  with  $w_1 = 0.5$

R2:  $y_2 = 25$  with  $w_2 = 1$

R3:  $y_3 = 17$  with  $w_3 = 0.5$

R4:  $y_4 = 11$  with  $w_4 = 0.5$

Using weighted average method

$$y^{crisp} = \frac{w_1 y_1 + w_2 y_2 + w_3 y_3 + w_4 y_4}{w_1 + w_2 + w_3 + w_4}$$

$$y^{crisp} = \frac{0.5 * 24 + 1 * 25 + 0.5 * 17 + 0.5 * 11}{0.5 + 1 + 0.5 + 0.5}$$

$$y^{crisp} = 20.4$$

